

rl_basicray
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1 rl_BasicRay User's Guide

1.1 Copyright and License

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1.2 Purpose

The `rl_BasicRay` library consists of a set of C++ classes for manipulating rays.

1.3 A Basic Ray Class

The `rl_BasicRay` class represents a stripped-down ray consisting of position, direction, energy, and an id number. It serves as a base class for a more general ray class `rl_Ray` (part of the `rl_raylib` package) which adds in support for ray polarization information.

The `rl_BasicRay` library includes a class encapsulating a basic ray consisting of position and direction information, ray energy, and a ray id number.

The ray is nominally defined in a standard coordinate system (STD) which serves as a default global coordinate system. The ray can be transformed into a local “body-centered” coordinate system (BCS) (e.g., attached to a piece of hardware such as a mirror).

In transforming from the STD system to the BCS system, the ray is first translated by the difference between the BCS origin and the STD origin, then transformed to the orientation of the BCS system relative to the STD system by rotation about the BCS origin.

To transform back to the STD system the operations are performed in reverse: first “derotate” the vector about the BCS origin to account for the different orientation, then “detranslate” the position by the difference between the BCS and STD origins.

Other operations on a basic ray include projection (moving the ray position by a given distance in the direction specified by the ray direction vector) and reflection of the ray direction vector about a surface normal provided by the user. In the reflection operation, it is assumed that the ray position is at the surface about which the reflection takes place.

2 Directory Hierarchy

2.1 Directories

This directory hierarchy is sorted roughly, but not completely, alphabetically:

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3 Class Index

3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

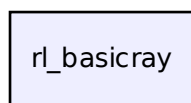
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4 Directory Documentation

4.1 rl_basicray/ Directory Reference

Directory dependency graph for rl_basicray/:



Files

- file [rl_BasicRay.cc](#)
- file [rl_BasicRay.h](#)
- file [rl_RayMath.h](#)

5 Class Documentation

5.1 rl_BasicRay Class Reference

```
#include <rl_BasicRay.h>
```

Public Member Functions

- virtual [~rl_BasicRay](#) ()
A virtual do-nothing destructor.
- [rl_BasicRay](#) ()
- [rl_BasicRay](#) (dvm3_Vector const &pos, dvm3_Vector const &dir, double energy, long int id)
- [rl_BasicRay](#) ([rl_BasicRay](#) const &other)
- void [set_id](#) (long int id)
- long int [id](#) () const
- double & [energy](#) ()
- double [energy](#) () const
- double & [position](#) (int i)
- double [position](#) (int i) const
- dvm3_Vector & [position](#) ()
- dvm3_Vector const & [position](#) () const
- double & [direction](#) (int i)
- double [direction](#) (int i) const
- dvm3_Vector & [direction](#) ()
- dvm3_Vector const & [direction](#) () const
- double [reflect_direction_vector](#) (dvm3_Vector const &normal)
- void [project](#) (double s)
- virtual void [translate_rotate](#) (dvm3_Vector const &trans, dvm3_RotMat const &rotmat)
- virtual void [derotate_detranslate](#) (dvm3_Vector const &trans, dvm3_RotMat const &rotmat)
- std::ostream & [print_on](#) (std::ostream &os, char const prefix[]="", char const postfix[]="") const

Protected Member Functions

- void [init](#) (dvm3_Vector const &pos, dvm3_Vector const &dir, double energy, long int id)

Protected Attributes

- dvm3_Vector [pos_](#)
ray position
- dvm3_Vector [dir_](#)
ray direction vector (direction cosines)
- double [energy_](#)
ray energy
- long int [id_](#)
ray id number

Friends

- std::ostream & [operator<<](#) (std::ostream &os, [rl_BasicRay](#) const &)

5.1.1 Detailed Description

A basic ray: encapsulates position and direction vectors, energy, and ray id.
Definition at line 47 of file rl_BasicRay.h.

5.1.2 Constructor & Destructor Documentation

5.1.2.1 [rl_BasicRay::~~rl_BasicRay \(\)](#) [**virtual**]

A virtual do-nothing destructor.

Definition at line 41 of file rl_BasicRay.cc.

5.1.2.2 [rl_BasicRay::rl_BasicRay \(\)](#) [**inline**]

Default constructor; constructs a ray in an INVALID state. Use init to initialize the fields.

Definition at line 274 of file rl_BasicRay.h.

5.1.2.3 rl_BasicRay::rl_BasicRay (dvm3_Vector const & *pos*, dvm3_Vector const & *dir*, double *energy*, long int *id*) [inline]

Constructor. Construct an [rl_BasicRay](#) from ray initial position and direction vector, energy, and id number.

Parameters

pos ray initial position.
dir ray initial direction unit vector.
energy ray energy, in keV.
id ray id.

Definition at line 279 of file rl_BasicRay.h.

5.1.2.4 rl_BasicRay::rl_BasicRay (rl_BasicRay const & *other*) [inline]

Copy constructor

Parameters

other ray to be copied.

Definition at line 286 of file rl_BasicRay.h.

5.1.3 Member Function Documentation

5.1.3.1 void rl_BasicRay::derotate_detranslate (dvm3_Vector const & *trans*, dvm3_RotMat const & *rotmat*) [inline, virtual]

VIRTUAL: Derotate back to STD coordinates; detranslate back to STD origin

Parameters

trans translation vector.
rotmat rotation matrix to be applied. rotmat specifies a rotation from std to bcs; the inverse of rotmat is applied to the ray.

Definition at line 391 of file rl_BasicRay.h.

References [rl_RayMath::derotate\(\)](#), [dir_](#), and [pos_](#).

5.1.3.2 double & rl_BasicRay::direction (int *i*) [inline]

Read/write access to component *i* of current ray direction

Parameters

i index.

Definition at line 345 of file rl_BasicRay.h.

References `dir_`.

5.1.3.3 double rl_BasicRay::direction (int *i*) const [inline]

Read-only access to component *i* of current ray direction

Parameters

i index.

Returns

component *i* of the position vector.

Definition at line 350 of file rl_BasicRay.h.

References `dir_`.

5.1.3.4 dvm3_Vector & rl_BasicRay::direction () [inline]

Read/write access to current ray direction vector

Returns

reference to current ray direction vector `dvm3_Vector`

Definition at line 355 of file rl_BasicRay.h.

References `dir_`.

5.1.3.5 dvm3_Vector const & rl_BasicRay::direction () const [inline]

Read-only access to current ray direction vector

Returns

const reference to current ray direction vector `dvm3_Vector`

Definition at line 360 of file `rl_BasicRay.h`.

References `dir_`.

5.1.3.6 `double &rl_BasicRay::energy () [inline]`

Read/write access to current ray energy

Returns

a reference to the ray energy

Definition at line 315 of file `rl_BasicRay.h`.

References `energy_`.

5.1.3.7 `double rl_BasicRay::energy () const [inline]`

Read-only access to current ray position

Returns

the ray energy

Definition at line 320 of file `rl_BasicRay.h`.

References `energy_`.

5.1.3.8 `long int rl_BasicRay::id () const [inline]`

Read-only access to current ray id

Returns

ray id number

Definition at line 306 of file `rl_BasicRay.h`.

References `id_`.

5.1.3.9 `void rl_BasicRay::init (dvm3_Vector const & pos, dvm3_Vector const & dir, double energy, long int id) [inline, protected]`

Initialize `rl_BasicRay` with ray initial position and direction vector, energy, and id number

Parameters

pos ray position vector
dir ray direction vector
energy ray energy
id ray id number

Definition at line 292 of file rl_BasicRay.h.

References `dir_`, `energy_`, `id_`, and `pos_`.

5.1.3.10 dvm3_Vector & rl_BasicRay::position () [inline]

Read/write access to current ray position

Returns

a reference to the position vector `dvm3_Vector`.

Definition at line 335 of file rl_BasicRay.h.

References `pos_`.

5.1.3.11 dvm3_Vector const & rl_BasicRay::position () const [inline]

Read-only access to current ray position

Returns

a const reference to the position vector `dvm3_Vector`

Definition at line 340 of file rl_BasicRay.h.

References `pos_`.

5.1.3.12 double & rl_BasicRay::position (int i) [inline]

Read/write access to component *i* of current ray position

Parameters

i index.

Returns

a reference to the *i* component of the position vector.

Definition at line 325 of file rl_BasicRay.h.

References `pos_`.

5.1.3.13 double rl_BasicRay::position (int *i*) const [inline]

Read-only access to component *i* of current ray position

Parameters

i index.

Returns

the *i* component of the position vector.

Definition at line 330 of file rl_BasicRay.h.

References pos_.

5.1.3.14 std::ostream& rl_BasicRay::print_on (std::ostream & *os*, char const *prefix*[] = "", char const *postfix*[] = "") const

Print the ray properties to an output stream.

Parameters

os output stream.

prefix an optional prefix string.

postfix an optional postfix string.

Returns

output stream

5.1.3.15 void rl_BasicRay::project (double *s*) [inline]

Project a distance *s* along this ray

Parameters

s distance to project the ray.

Definition at line 369 of file rl_BasicRay.h.

References dir_, and pos_.

5.1.3.16 double rl_BasicRay::reflect_direction_vector (dvm3_Vector const & *normal*)

Reflect this ray's direction vector about a (surface) normal

Parameters

normal - surface normal unit vector to be used in reflecting this [rl_BasicRay](#).

Returns

sine of the graze angle between the ray and the surface

Definition at line 52 of file rl_BasicRay.cc.

References `dir_`.

5.1.3.17 void rl_BasicRay::set_id (long int *id*) [inline]

Reset ray id

Parameters

id new id value.

Definition at line 310 of file rl_BasicRay.h.

References `id_`.

5.1.3.18 void rl_BasicRay::translate_rotate (dvm3_Vector const & *trans*, dvm3_RotMat const & *rotmat*) [inline, virtual]

VIRTUAL: Translate to the BCS origin; rotate from STD to BCS coordinates

Parameters

trans translation vector.

rotmat rotation matrix to be applied. `rotmat` specifies a rotation from `std` to `bcs`.

Definition at line 379 of file rl_BasicRay.h.

References `dir_`, `pos_`, and `rl_RayMath::rotate()`.

5.1.4 Friends And Related Function Documentation

5.1.4.1 `std::ostream& operator<< (std::ostream & os, rl_BasicRay const &) [friend]`

Print the ray properties to an output stream.

Parameters

os output stream.

Returns

output stream

5.1.5 Member Data Documentation

5.1.5.1 `dvm3_Vector rl_BasicRay::dir_ [protected]`

ray direction vector (direction cosines)

Definition at line 54 of file rl_BasicRay.h.

Referenced by `derotate_detranslate()`, `direction()`, `init()`, `project()`, `reflect_direction_vector()`, and `translate_rotate()`.

5.1.5.2 `double rl_BasicRay::energy_ [protected]`

ray energy

Definition at line 56 of file rl_BasicRay.h.

Referenced by `energy()`, and `init()`.

5.1.5.3 `long int rl_BasicRay::id_ [protected]`

ray id number

Definition at line 58 of file rl_BasicRay.h.

Referenced by `id()`, `init()`, and `set_id()`.

5.1.5.4 dvm3_Vector rl_BasicRay::pos_ [protected]

ray position

Definition at line 52 of file rl_BasicRay.h.

Referenced by `derotate_detranslate()`, `init()`, `position()`, `project()`, and `translate_rotate()`.

The documentation for this class was generated from the following files:

- `rl_BasicRay.h`
- `rl_BasicRay.cc`

5.2 rl_RayMath Class Reference

```
#include <rl_RayMath.h>
```

Static Public Member Functions

- static void [rotate](#) (dvm3_RotMat const &rotmat, dvm3_Vector &vector)
- static void [rotate](#) (dvm3_RotMat const &rotmat, double vector[])
- static void [derotate](#) (dvm3_RotMat const &rotmat, dvm3_Vector &vector)
- static void [derotate](#) (dvm3_RotMat const &rotmat, double vector[])
- static void [translate_rotate](#) (dvm3_Vector const &trans, dvm3_RotMat const &rotmat, dvm3_Vector &vector)
- static void [translate_rotate](#) (double const trans[], dvm3_RotMat const &rotmat, double vector[])
- static void [derotate_detranslate](#) (dvm3_Vector const &trans, dvm3_RotMat const &rotmat, dvm3_Vector &vector)
- static void [derotate_detranslate](#) (double const trans[], dvm3_RotMat const &rotmat, double vector[])

5.2.1 Detailed Description

A class gathering together static methods for operations on ray position or direction vectors.

The class is a simple class to handle common numerical operations on 3-vectors of floating point T_fps representing ray position vectors and ray direction vectors.

[rl_RayMath](#) has only static member functions; there are no member data. Where possible, the static member functions are inlined.

The static member functions facilitate transformations between an initial coordinate system (termed "Standard" or STD) and another coordinate system (termed "Body Centered" or BCS). This is just convenient labeling which reflects a common usage of the transformations.

The BCS coordinate origin is (optionally) translated relative to the STD origin, and the orientation of the BCS coordinate axes relative to the STD axes is described by a proper rotation matrix.

The transformation from STD to BCS is accomplished by "rotate_translate" (or "rotate" if the coordinate origins are coincident).

The transformation from BCS back to STD is accomplished by "detranslate_derotate" (or "derotate" if the coordinate origins are coincident).

Direction vectors are always transformed using the "rotate"-"derotate" pair, NEVER the versions involving translation.

Positional vectors are transformed using "rotate_translate" and "detranslate_derotate"; if the STD and BCS coordinate systems origins are coincident, the transformation can be accomplished more economically using the "rotate" and "derotate" pair.

NOTE: although dvm3_Matrix works with either dvm3_Vector's or plain old c-style one-dimensional arrays, any call to an [rl_RayMath](#) method must use only one vector type within a given method call.

Definition at line 91 of file rl_RayMath.h.

5.2.2 Member Function Documentation

5.2.2.1 void rl_RayMath::derotate (dvm3_RotMat const & *rotmat*, dvm3_Vector & *vector*) [inline, static]

De-rotate vector from BCS coordinates back to STD coordinates.

Parameters

rotmat rotation vector (STD to BCS) to be used. The *INVERSE* of rotmat is applied to the vector.

vector vector to be rotated.

Definition at line 219 of file rl_RayMath.h.

Referenced by rl_BasicRay::derotate_detranslate().

5.2.2.2 void rl_RayMath::derotate (dvm3_RotMat const & *rotmat*, double *vector*[]) [inline, static]

De-rotate vector from BCS coordinates back to STD coordinates.

Parameters

rotmat rotation vector (STD to BCS) to be used. The *INVERSE* of rotmat is applied to the vector.

vector c-style vector to be rotated.

Definition at line 228 of file rl_RayMath.h.

5.2.2.3 `void rl_RayMath::derotate_detranslate (double const trans[],
dvm3_RotMat const & rotmat, double vector[]) [inline,
static]`

Rotate from BCS to STD coordinates, then translate back to original position. This is the inverse operation to translate_rotate.

Parameters

trans c-style translation vector.

rotmat rotation vector (STD to BCS) to be applied.

vector c-style vector to be derotated.

Definition at line 278 of file rl_RayMath.h.

5.2.2.4 `void rl_RayMath::derotate_detranslate (dvm3_Vector const & trans,
dvm3_RotMat const & rotmat, dvm3_Vector & vector) [inline,
static]`

Rotate from BCS to STD coordinates, then translate back to original position. This is the inverse operation to translate_rotate.

Parameters

trans translation vector.

rotmat rotation vector (STD to BCS) to be applied.

vector c-style vector to be derotated.

Definition at line 267 of file rl_RayMath.h.

5.2.2.5 `void rl_RayMath::rotate (dvm3_RotMat const & rotmat,
dvm3_Vector & vector) [inline, static]`

Rotate vector from STD coordinates to BCS coordinates.

Parameters

rotmat rotation vector (STD to BCS) to be applied.

vector vector to be rotated.

Definition at line 197 of file rl_RayMath.h.

Referenced by rl_BasicRay::translate_rotate().

5.2.2.6 `void rl_RayMath::rotate (dvm3_RotMat const & rotmat, double vector[]) [inline, static]`

Rotate vector from STD coordinates to BCS coordinates.

Parameters

rotmat rotation vector (STD to BCS) to be applied.

vector c-style vector to be rotated.

Definition at line 206 of file rl_RayMath.h.

5.2.2.7 `void rl_RayMath::translate_rotate (double const trans[], dvm3_RotMat const & rotmat, double vector[]) [inline, static]`

Translate to BCS origin, then rotate from STD to BCS coordinates.

Parameters

trans translation vector.

rotmat rotation vector (STD to BCS) to be applied.

vector c-style vector to be derotated.

Definition at line 252 of file rl_RayMath.h.

5.2.2.8 `void rl_RayMath::translate_rotate (dvm3_Vector const & trans, dvm3_RotMat const & rotmat, dvm3_Vector & vector) [inline, static]`

Translate to BCS origin, then rotate from STD to BCS coordinates.

Parameters

trans translation vector.

rotmat rotation vector (STD to BCS) to be applied.

vector vector to be derotated.

Definition at line 241 of file rl_RayMath.h.

The documentation for this class was generated from the following file:

- rl_RayMath.h

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