

vm\_math  
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## 1 The vm\_Math C++ template Library

### 1.1 Copyright

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### 1.2 Overview

The vm\_math C++ library is a collection of templated routines to deal efficiently with low-level floating point vectors, 3-vectors, and 3x3 matrices. It is split up into several sub-packages (see the **Modules** page for more information).

The vm\_math package brings together a number of functions for operating on 3-vectors and 3-matrices, and for creating orthonormal 3-matrices corresponding to proper rotations (i.e., orthonormal matrices preserving the coordinate system parity).

These are implemented as inlined static member functions; the functions are bundled into classes in order to take them out of the global namespace. By making the functions static member functions, they can be called without recourse to an instantiated object, e.g.

```
double v1[] = { 1.3, 2.4, 7.2, 9.7 };
double v2[] = { 7.2, 1.9, 3.1, 4.1 };
double foo = vm_VMath<double,4>::dot( v2, v1 );
```

The package currently contains 3 classes:

- `vm_VMath<T_fp,N_len>`: common numerical operations on `N_len`-long one-dimensional arrays of floating point type `T_fp`. This class captures operations which do not depend on the explicit 3-vector or 3x3-matrix properties.

- `vm_V3math<T_fp>`: common numerical operations on 3-vectors of floating point type `T_fp`. Publicly derives from `vm_VMath<T_fp,3>`. This class adds in specifically 3-vector functionality such as vector cross products.
- `vm_M3math<T_fp>`: common numerical operations on 3x3 matrices of floating point type `T_fp`. The matrix is assumed to be stored as a contiguous one-dimensional array of 9 `T_fp`'s. Publicly derives from `vm_VMath<T_fp,9>`. This class adds in specifically matrix properties such as multiplication and matrix-vector multiplication.

All members are inlined, so the package consists only of header files.

### 1.3 vm\_VMath common numerical operations

on `N_len`-long \* 1 dimensional arrays of `T_fp`

These routines provide the basic low-level support for 1-dimensional arrays of floating point values. The library is a C++ template library, with template parameters `T_fp` and `N_len`. `T_fp` is the floating point type. It must be a simple type (float or double), since it is assumed that the array can be copied as plain ol' data using `memcpy`. `N_len` is the dimension of the vector, assumed to be small, e.g., 9 for a flat representation of a 3x3 matrix. The class has no state information with all functionality implemented as (we hope) inlined functions.

To use these routines, ensure that you include the correct header file:

```
#include <vm_vmath/vm_vmath.h>
```

or

```
#include <vm_vmath/vm_math.h>
```

### 1.4 vm\_V3Math common numerical operations

on 3-vectors of floating point values

These routines provide the basic low-level support for 3-vectors of floating point values of type `T_fp` (float or double). The library is a C++ template library, templized on `T_fp`.

To use these routines, ensure that you include the correct header file:

```
#include <vm_vmath/vm_v3math.h>
```

or

```
#include <vm_vmath/vm_math.h>
```

### 1.5 vm\_M3math common numerical operations

on 3x3 matrices of floating point values

These routines provide the basic low-level support for 3x3 matrices of floating point values of type `T_fp` (float or double). The library is a C++ template library, templized on `T_fp`.

To use these routines, ensure that you include the correct header file:

```
#include <vm_vmath/vm_m3math.h>
```

or

```
#include <vm_vmath/vm_math.h>
```

## 2 Module Index

### 2.1 Modules

Here is a list of all modules:

<b>vm_VMath common numerical operations</b>	<b>4</b>
<b>vm_V3Math common numerical operations</b>	<b>5</b>
<b>vm_M3Math common numerical operations</b>	<b>6</b>
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## 3 Hierarchical Index

### 3.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

<b>vm_VMath&lt; T_fp, N_len &gt;</b>	<b>32</b>
<b>vm_VMath&lt; T_fp, 3 &gt;</b>	<b>32</b>

<a href="#">vm_V3Math&lt; T_fp &gt;</a>	<a href="#">30</a>
<a href="#">vm_VMath&lt; T_fp, 9 &gt;</a>	<a href="#">32</a>
<a href="#">vm_M3Math&lt; T_fp &gt;</a>	<a href="#">29</a>

## 4 Class Index

### 4.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

<a href="#">vm_M3Math&lt; T_fp &gt;</a>	<a href="#">29</a>
<a href="#">vm_V3Math&lt; T_fp &gt;</a>	<a href="#">30</a>
<a href="#">vm_VMath&lt; T_fp, N_len &gt;</a>	<a href="#">32</a>

## 5 Module Documentation

### 5.1 vm\_VMath common numerical operations

## 5.2 `vm_V3Math` common numerical operations



### 5.3 vm\_M3Math common numerical operations

## 5.4 Index calculations

### Functions

- static int `vm_M3Math< T_fp >::at` (int *i*, int *j*)

#### 5.4.1 Detailed Description

#### 5.4.2 Function Documentation

##### 5.4.2.1 `template<class T_fp> int vm_M3Math< T_fp >::at ( int i, int j )` `[inline], [static]`

Index calculation.

Array value `m[i][j]` is `*(m + i*EColStride + j)`

### Returns

offset of index set *i*, *j* (used for flat array storage)

### Parameters

<i>i</i>	index
<i>j</i>	index

Definition at line 290 of file `vm_m3math.h`.

## 5.5 Initialize a matrix.

### Functions

- static void `vm_M3Math< T_fp >::init_by_row` (T\_fp m[], T\_fp const row0[], T\_fp const row1[], T\_fp const row2[])
- static void `vm_M3Math< T_fp >::init_by_col` (T\_fp m[], T\_fp const col0[], T\_fp const col1[], T\_fp const col2[])
- static void `vm_M3Math< T_fp >::dyad_product` (T\_fp m[], T\_fp const v1[], T\_fp const v2[])

#### 5.5.1 Detailed Description

#### 5.5.2 Function Documentation

**5.5.2.1** `template<class T_fp > void vm_M3Math< T_fp >::dyad_product ( T_fp m[], T_fp const v1[], T_fp const v2[] )`  
`[inline], [static]`

Initialize a matrix to a dyadic (outer) product of vectors

For each i, j:  $m[at(i,j)] = v1[i] * v2[j]$

#### Parameters

<i>m</i>	matrix (as stored flat 1D array)
<i>v1</i>	1st vector
<i>v2</i>	2nd vector

Definition at line 361 of file `vm_m3math.h`.

**5.5.2.2** `template<class T_fp > void vm_M3Math< T_fp >::init_by_col ( T_fp m[], T_fp const col0[], T_fp const col1[], T_fp const col2[] )`  
`[inline], [static]`

Initialize matrix by column; set columns of m to col0, col1, col2.

#### Parameters

<i>m</i>	matrix (as stored flat 1D array)
<i>col0</i>	1st column vector
<i>col1</i>	2nd column vector
<i>col2</i>	3rd column vector

Definition at line 308 of file `vm_m3math.h`.

**5.5.2.3** `template<class T_fp > void vm_M3Math< T_fp >::init_by_row ( T_fp m[], T_fp const row0[], T_fp const row1[], T_fp const row2[] )`  
`[inline], [static]`

Initialize matrix by row; set rows of m to row0, row1, row2.

#### Parameters

<i>m</i>	matrix (as stored flat 1D array)
<i>row0</i>	1st row vector
<i>row1</i>	2nd row vector
<i>row2</i>	3rd row vector

Definition at line 298 of file `vm_m3math.h`.

## 5.6 For a matrix, insert or extract a vector.

### Functions

- static void [vm\\_M3Math< T\\_fp >::inject\\_row](#) (T\_fp m[], T\_fp const row[], int whichrow)
- static void [vm\\_M3Math< T\\_fp >::inject\\_col](#) (T\_fp m[], T\_fp const col[], int whichcol)
- static void [vm\\_M3Math< T\\_fp >::extract\\_row](#) (T\_fp const m[], T\_fp row[], int whichrow)
- static void [vm\\_M3Math< T\\_fp >::extract\\_col](#) (T\_fp const m[], T\_fp col[], int whichcol)

### 5.6.1 Detailed Description

### 5.6.2 Function Documentation

**5.6.2.1** `template<class T_fp > void vm_M3Math< T_fp >::extract_col ( T_fp const m[], T_fp col[], int whichcol )`  
`[inline], [static]`

Copy a given column of m to a vector.

#### Parameters

<i>m</i>	matrix (as stored flat 1D array)
<i>col</i>	vector to receive the copy
<i>whichcol</i>	column index

Definition at line 347 of file vm\_m3math.h.

**5.6.2.2** `template<class T_fp > void vm_M3Math< T_fp >::extract_row ( T_fp const m[], T_fp row[], int whichrow )`  
`[inline], [static]`

Copy a given row of m to a vector.

#### Parameters

<i>m</i>	matrix (as stored flat 1D array)
<i>row</i>	vector to receive the copy
<i>whichrow</i>	row index

Definition at line 341 of file vm\_m3math.h.

**5.6.2.3** `template<class T_fp > void vm_M3Math< T_fp >::inject_col ( T_fp m[], T_fp const col[], int whichcol )` `[inline], [static]`

Copy a vector to a given column of m.

#### Parameters

<i>m</i>	matrix (as stored flat 1D array)
<i>col</i>	vector to be stored
<i>whichcol</i>	column index

Definition at line 327 of file vm\_m3math.h.

5.6.2.4 `template<class T_fp > void vm_M3Math< T_fp >::inject_row ( T_fp m[], T_fp const row[], int whichrow )`  
`[inline],[static]`

Copy a vector to a given row of m.

#### Parameters

<i>m</i>	matrix (as stored flat 1D array)
<i>row</i>	vector to be stored
<i>whichrow</i>	row index

Definition at line 321 of file vm\_m3math.h.

## 5.7 Matrix Vector operations.

### Functions

- static void `vm_M3Math< T_fp >::mvmult` (T\_fp res[], T\_fp const m[], T\_fp const v[])
- static void `vm_M3Math< T_fp >::mtvmult` (T\_fp res[], T\_fp const m[], T\_fp const v[])

#### 5.7.1 Detailed Description

#### 5.7.2 Function Documentation

5.7.2.1 `template<class T_fp > void vm_M3Math< T_fp >::mtvmult ( T_fp res[], T_fp const m[], T_fp const v[] )` `[inline]`,  
`[static]`

Matrix multiplication of vector v by transpose of matrix m.

result = m\_transpose *matrix\_multiply* v.

#### Parameters

<i>res</i>	resulting matrix (as stored flat 1D array)
<i>m</i>	matrix to be transposed and multiplied
<i>v</i>	vector to be multiplied

Definition at line 382 of file vm\_m3math.h.

5.7.2.2 `template<class T_fp > void vm_M3Math< T_fp >::mvmult ( T_fp res[], T_fp const m[], T_fp const v[] )` `[inline]`,  
`[static]`

Matrix multiplication of vector v by matrix m.

result = m *matrix\_multiply* v.

#### Parameters

<i>res</i>	resulting matrix (as stored flat 1D array)
<i>m</i>	matrix to be multiplied
<i>v</i>	vector to be multiplied

Definition at line 373 of file vm\_m3math.h.

## 5.8 Matrix Matrix operations.

### Functions

- static void **vm\_M3Math**< **T\_fp** >::**mmult** (T\_fp mres[], T\_fp const m1[], T\_fp const m2[])

#### 5.8.1 Detailed Description

## 5.9 IO operations.

### Functions

- static std::ostream & [vm\\_M3Math< T\\_fp >::print\\_on](#) (std::ostream &os, T\_fp const m[], char const prefix[]="", char const postfix[]="")
- static void [vm\\_M3Math< T\\_fp >::cprint\\_on](#) (FILE \*of, T\_fp const m[], char const prefix[]="", char const postfix[]="")

#### 5.9.1 Detailed Description

#### 5.9.2 Function Documentation

**5.9.2.1** `template<class T_fp > void vm_M3Math< T_fp >::cprint_on ( FILE * of, T_fp const m[], char const prefix[] = " ", char const postfix[] = " " ) [inline],[static]`

Print a matrix to a FILE\* stream.

##### Parameters

<i>of</i>	the FILE*
<i>m</i>	matrix to be printed
<i>prefix</i>	optional prefix string
<i>postfix</i>	optional postfix string

Definition at line 421 of file vm\_m3math.h.

**5.9.2.2** `template<class T_fp > std::ostream & vm_M3Math< T_fp >::print_on ( std::ostream & os, T_fp const m[], char const prefix[] = " ", char const postfix[] = " " ) [inline],[static]`

Print a matrix to an ostream.

##### Parameters

<i>os</i>	the ostream
<i>m</i>	matrix to be printed
<i>prefix</i>	optional prefix string
<i>postfix</i>	optional postfix string

Definition at line 408 of file vm\_m3math.h.



## 5.10 Set vector components

### Functions

- static void `vm_V3Math< T_fp >::set` (T\_fp v[], T\_fp x, T\_fp y, T\_fp z)
- static void `vm_V3Math< T_fp >::set` (T\_fp v[], T\_fp x)

#### 5.10.1 Detailed Description

#### 5.10.2 Function Documentation

5.10.2.1 `template<class T_fp > void vm_V3Math< T_fp >::set ( T_fp v[], T_fp x, T_fp y, T_fp z )` `[inline], [static]`

Set components of v to x, y, z.

##### Parameters

v	vector to be set
x	x component
y	y component
z	z component

Definition at line 255 of file `vm_v3math.h`.

5.10.2.2 `template<class T_fp > void vm_V3Math< T_fp >::set ( T_fp v[], T_fp x )` `[inline], [static]`

Set all components of v to x.

##### Parameters

v	vector to be set
x	value

Definition at line 260 of file `vm_v3math.h`.

References `vm_VMath< T_fp, N_len >::set()`.

## 5.11 Normalize vectors

### Functions

- static `T_fp vm_V3Math< T_fp >::unitize (T_fp v[])`
- static `T_fp vm_V3Math< T_fp >::unitize (T_fp vu[], T_fp const vi[])`

#### 5.11.1 Detailed Description

#### 5.11.2 Function Documentation

##### 5.11.2.1 `template<class T_fp> T_fp vm_V3Math< T_fp >::unitize ( T_fp v[] ) [inline], [static]`

Normalize a vector v.

#### Returns

return original vector magnitude

#### Parameters

<i>v</i>	vector to be normalized
----------	-------------------------

Definition at line 282 of file `vm_v3math.h`.

Referenced by `vm_V3Math< T_fp >::unitize()`.

##### 5.11.2.2 `template<class T_fp> T_fp vm_V3Math< T_fp >::unitize ( T_fp vu[], T_fp const vi[] ) [inline], [static]`

Normalize a vector vi returning the normalized value in vu.

#### Returns

return original magnitude of vi

#### Parameters

<i>vi</i>	vector to be normalized
<i>vu</i>	normalized version of vi

Definition at line 296 of file `vm_v3math.h`.

References `vm_VMath< T_fp, 3 >::copy()`, and `vm_V3Math< T_fp >::unitize()`.

## 5.12 Tests for normality, orthogonality

### Functions

- static int `vm_V3Math< T_fp >::is_unit_vector` (T\_fp const v[], T\_fp const tol)
- static int `vm_V3Math< T_fp >::are_orthogonal` (T\_fp const v[], T\_fp const other[], T\_fp const tol)
- static int `vm_V3Math< T_fp >::are_orthonormal` (T\_fp const v[], T\_fp const other[], T\_fp const tol)

#### 5.12.1 Detailed Description

#### 5.12.2 Function Documentation

5.12.2.1 `template<class T_fp > int vm_V3Math< T_fp >::are_orthogonal ( T_fp const v[], T_fp const other[], T_fp const tol )`  
`[inline], [static]`

Test whether a v is within tolerance tol of orthogonality to other vector

#### Returns

1 if v and other are orthogonal within tolerance tol, 0 otherwise.

#### Parameters

<i>v</i>	vector to be checked
<i>other</i>	other vector
<i>tol</i>	tolerance

Definition at line 311 of file `vm_v3math.h`.

5.12.2.2 `template<class T_fp > int vm_V3Math< T_fp >::are_orthonormal ( T_fp const v[], T_fp const other[], T_fp const tol )`  
`[inline], [static]`

Test whether v is within tolerance tol of orthonormality with other vector

#### Returns

1 if v and other are orthonormal within tolerance tol, 0 otherwise.

#### Parameters

<i>v</i>	vector to be checked
<i>other</i>	other vector
<i>tol</i>	tolerance

Definition at line 320 of file `vm_v3math.h`.

5.12.2.3 `template<class T_fp > int vm_V3Math< T_fp >::is_unit_vector ( T_fp const v[], T_fp const tol )` `[inline], [static]`

Test whether a vector is within tolerance tol of a unit vector

**Returns**

1 if  $v$  is within tolerance  $tol$  of being a unit vector, 0 otherwise.

**Parameters**

$v$	vector to be checked
$tol$	tolerance

Definition at line 304 of file `vm_v3math.h`.

## 5.13 Dot and Cross products.

### Functions

- static `T_fp vm_V3Math< T_fp >::dot` (`T_fp const v1[]`, `T_fp const v2[]`)
- static void `vm_V3Math< T_fp >::cross` (`T_fp prod[]`, `T_fp const v1[]`, `T_fp const v2[]`)

#### 5.13.1 Detailed Description

#### 5.13.2 Function Documentation

5.13.2.1 `template<class T_fp > void vm_V3Math< T_fp >::cross ( T_fp prod[], T_fp const v1[], T_fp const v2[] )`  
`[inline], [static]`

Cross (wedge) product of two vectors

#### Returns

cross (wedge) product of v1 with v2.

#### Parameters

<i>prod</i>	cross (wedge) product of v1 with v2.
<i>v1</i>	1st vector
<i>v2</i>	2nd vector

Definition at line 272 of file `vm_v3math.h`.

5.13.2.2 `template<class T_fp > T_fp vm_V3Math< T_fp >::dot ( T_fp const v1[], T_fp const v2[] )` `[inline], [static]`

Dot product of two vectors

#### Returns

dot (scalar) product of v1 with v2.

#### Parameters

<i>v1</i>	1st vector
<i>v2</i>	2nd vector

Definition at line 265 of file `vm_v3math.h`.

## 5.14 IO operations.

## Functions

- static std::ostream & [vm\\_V3Math< T\\_fp >::print\\_on](#) (std::ostream &os, T\_fp const v[], char const prefix[]="", char const postfix[]="")
- static void [vm\\_V3Math< T\\_fp >::cprint\\_on](#) (FILE \*of, T\_fp const v[], char const prefix[]="", char const postfix[]="")

## 5.14.1 Detailed Description

## 5.14.2 Function Documentation

5.14.2.1 `template<class T_fp > void vm_V3Math< T_fp >::cprint_on ( FILE * of, T_fp const v[], char const prefix[] = " ", char const postfix[] = " " ) [inline],[static]`

Print a vector to a FILE\* stream.

## Parameters

<i>of</i>	the FILE*
<i>v</i>	vector to be printed
<i>prefix</i>	optional prefix string
<i>postfix</i>	optional postfix string

Definition at line 340 of file vm\_v3math.h.

5.14.2.2 `template<class T_fp > std::ostream & vm_V3Math< T_fp >::print_on ( std::ostream & os, T_fp const v[], char const prefix[] = " ", char const postfix[] = " " ) [inline],[static]`

Print a vector to an ostream.

## Parameters

<i>os</i>	the ostream
<i>v</i>	vector to be printed
<i>prefix</i>	optional prefix string
<i>postfix</i>	optional postfix string

Definition at line 331 of file vm\_v3math.h.

## 5.15 Copy routines

### Functions

- static void `vm_VMath< T_fp, N_len >::copy` (T\_fp v[], T\_fp const cv[])

#### 5.15.1 Detailed Description

#### 5.15.2 Function Documentation

5.15.2.1 `template<class T_fp, int N_len> void vm_VMath< T_fp, N_len >::copy ( T_fp v[], T_fp const cv[] )` `[inline]`,  
`[static]`

Normalize a vector v.

#### Parameters

v	destination vector
cv	source vector

REQUIREMENT: \*v and \*cv each has a length of at least N\_len contiguous T\_fps and is appropriately aligned for T\_fps.

Definition at line 385 of file vm\_vmath.h.

## 5.16 Set functions

### Functions

- static void `vm_VMath< T_fp, N_len >::set (T_fp v[], T_fp r)`

#### 5.16.1 Detailed Description

#### 5.16.2 Function Documentation

5.16.2.1 `template<class T_fp, int N_len> void vm_VMath< T_fp, N_len >::set ( T_fp v[], T_fp r )` `[inline],[static]`

Set all elements of `v` to `r`.

#### Parameters

<code>v</code>	vector to be set
<code>r</code>	value

Definition at line 393 of file `vm_vmath.h`.

Referenced by `vm_V3Math< T_fp >::set()`.



## 5.17 Componentwise op\_eq operations (+=, -=, /=)

## Functions

- static void `vm_VMath< T_fp, N_len >::add_eq` (T\_fp v[], T\_fp const cv[])
- static void `vm_VMath< T_fp, N_len >::sub_eq` (T\_fp v[], T\_fp const cv[])
- static void `vm_VMath< T_fp, N_len >::mul_eq` (T\_fp v[], T\_fp const cv[])
- static void `vm_VMath< T_fp, N_len >::div_eq` (T\_fp v[], T\_fp const cv[])
- static void `vm_VMath< T_fp, N_len >::add_eq` (T\_fp v[], T\_fp r)
- static void `vm_VMath< T_fp, N_len >::sub_eq` (T\_fp v[], T\_fp r)
- static void `vm_VMath< T_fp, N_len >::mul_eq` (T\_fp v[], T\_fp r)
- static void `vm_VMath< T_fp, N_len >::div_eq` (T\_fp v[], T\_fp r)
- static void `vm_VMath< T_fp, N_len >::negate` (T\_fp v[])

## 5.17.1 Detailed Description

## 5.17.2 Function Documentation

5.17.2.1 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::add_eq ( T_fp v[], T_fp const cv[] )` `[inline], [static]`

component-wise  $v[n] += cv[n]$

## Parameters

<code>v</code>	LHS vector
<code>cv</code>	RHS vector

5.17.2.2 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::add_eq ( T_fp v[], T_fp r )` `[inline], [static]`

component-wise  $v[n] += r$

## Parameters

<code>v</code>	LHS vector
<code>r</code>	RHS T_fp

5.17.2.3 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::div_eq ( T_fp v[], T_fp const cv[] )` `[inline], [static]`

component-wise  $v[n] /= cv[n]$

## Parameters

<code>v</code>	LHS vector
<code>cv</code>	RHS vector

5.17.2.4 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::div_eq ( T_fp v[], T_fp r )` `[inline], [static]`

component-wise  $v[n] /= r$

## Parameters

$v$	LHS vector
$r$	RHS T_fp

**5.17.2.5** `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::mul_eq ( T_fp v[], T_fp const cv[] )`  
`[inline], [static]`

component-wise  $v[n] *= cv[n]$

## Parameters

$v$	LHS vector
$cv$	RHS vector

**5.17.2.6** `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::mul_eq ( T_fp v[], T_fp r )` `[inline],`  
`[static]`

component-wise  $v[n] *= r$

## Parameters

$v$	LHS vector
$r$	RHS T_fp

**5.17.2.7** `template<class T_fp, int N_len> int N_len void vm_VMath< T_fp, N_len >::negate ( T_fp v[] )` `[inline],`  
`[static]`

component-wise negation of  $v$

## Parameters

$v$	vector
-----	--------

Definition at line 414 of file vm\_vmath.h.

**5.17.2.8** `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::sub_eq ( T_fp v[], T_fp const cv[] )`  
`[inline], [static]`

component-wise  $v[n] -= cv[n]$

## Parameters

$v$	LHS vector
$cv$	RHS vector

**5.17.2.9** `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::sub_eq ( T_fp v[], T_fp r )` `[inline],`  
`[static]`

component-wise  $v[n] -= r$

## Parameters

$v$	LHS vector
$r$	RHS T_fp

## 5.18 {add,sub,mul,div}: componentwise binary operations.

## Functions

- static void `vm_VMath< T_fp, N_len >::add` (T\_fp v[], T\_fp const cv1[], T\_fp const cv2[])
- static void `vm_VMath< T_fp, N_len >::sub` (T\_fp v[], T\_fp const cv1[], T\_fp const cv2[])
- static void `vm_VMath< T_fp, N_len >::mul` (T\_fp v[], T\_fp const cv1[], T\_fp const cv2[])
- static void `vm_VMath< T_fp, N_len >::div` (T\_fp v[], T\_fp const cv1[], T\_fp const cv2[])
- static void `vm_VMath< T_fp, N_len >::add` (T\_fp v[], T\_fp const cv[], T\_fp r)
- static void `vm_VMath< T_fp, N_len >::sub` (T\_fp v[], T\_fp const cv[], T\_fp r)
- static void `vm_VMath< T_fp, N_len >::mul` (T\_fp v[], T\_fp const cv[], T\_fp r)
- static void `vm_VMath< T_fp, N_len >::div` (T\_fp v[], T\_fp const cv[], T\_fp r)
- static void `vm_VMath< T_fp, N_len >::add` (T\_fp v[], T\_fp r, T\_fp const cv[])
- static void `vm_VMath< T_fp, N_len >::sub` (T\_fp v[], T\_fp r, T\_fp const cv[])
- static void `vm_VMath< T_fp, N_len >::mul` (T\_fp v[], T\_fp r, T\_fp const cv[])
- static void `vm_VMath< T_fp, N_len >::div` (T\_fp v[], T\_fp r, T\_fp const cv[])

## 5.18.1 Detailed Description

## 5.18.2 Function Documentation

5.18.2.1 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::add ( T_fp v[], T_fp const cv1[], T_fp const cv2[] ) [inline], [static]`

component-wise  $v[n] = cv1[n] + cv2[n]$

## Parameters

<code>v</code>	result vector
<code>cv1</code>	1st input vector
<code>cv2</code>	2nd input vector

5.18.2.2 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::add ( T_fp v[], T_fp const cv[], T_fp r ) [inline], [static]`

component-wise  $v[n] = cv[n] + r$

## Parameters

<code>v</code>	result vector
<code>cv</code>	input vector
<code>r</code>	input T_fp

5.18.2.3 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::add ( T_fp v[], T_fp r, T_fp const cv[] ) [inline], [static]`

component-wise  $v[n] = r + cv[n]$

## Parameters

<code>v</code>	result vector
<code>r</code>	input T_fp
<code>cv</code>	input vector

5.18.2.4 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::div ( T_fp v[], T_fp const cv1[], T_fp const cv2[] ) [inline],[static]`

component-wise  $v[n] = cv1[n] / cv2[n]$

Parameters

<code>v</code>	result vector
<code>cv1</code>	1st input vector
<code>cv2</code>	2nd input vector

5.18.2.5 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::div ( T_fp v[], T_fp const cv[], T_fp r ) [inline],[static]`

component-wise  $v[n] = cv[n] / r$

Parameters

<code>v</code>	result vector
<code>cv</code>	input vector
<code>r</code>	input T_fp

5.18.2.6 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::div ( T_fp v[], T_fp r, T_fp const cv[] ) [inline],[static]`

component-wise  $v[n] = r / cv[n]$

Parameters

<code>v</code>	result vector
<code>r</code>	input T_fp
<code>cv</code>	input vector

5.18.2.7 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::mul ( T_fp v[], T_fp const cv1[], T_fp const cv2[] ) [inline],[static]`

component-wise  $v[n] = cv1[n] * cv2[n]$

Parameters

<code>v</code>	result vector
<code>cv1</code>	1st input vector
<code>cv2</code>	2nd input vector

5.18.2.8 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::mul ( T_fp v[], T_fp const cv[], T_fp r ) [inline],[static]`

component-wise  $v[n] = cv[n] * r$

Parameters

<code>v</code>	result vector
<code>cv</code>	input vector
<code>r</code>	input T_fp

5.18.2.9 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::mul ( T_fp v[], T_fp r, T_fp const cv[] )`  
`[inline],[static]`

component-wise  $v[n] = r * cv[n]$

Parameters

<i>v</i>	result vector
<i>r</i>	input T_fp
<i>cv</i>	input vector

5.18.2.10 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::sub ( T_fp v[], T_fp const cv1[], T_fp const cv2[] )`  
`[inline],[static]`

component-wise  $v[n] = cv1[n] - cv2[n]$

Parameters

<i>v</i>	result vector
<i>cv1</i>	1st input vector
<i>cv2</i>	2nd input vector

5.18.2.11 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::sub ( T_fp v[], T_fp const cv[], T_fp r )`  
`[inline],[static]`

component-wise  $v[n] = cv[n] - r$

Parameters

<i>v</i>	result vector
<i>cv</i>	input vector
<i>r</i>	input T_fp

5.18.2.12 `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::sub ( T_fp v[], T_fp r, T_fp const cv[] )`  
`[inline],[static]`

component-wise  $v[n] = r - cv[n]$

Parameters

<i>v</i>	result vector
<i>r</i>	input T_fp
<i>cv</i>	input vector

## 5.19 Linear combinations

### Functions

- static void `vm_VMath< T_fp, N_len >::lincomb` (T\_fp res[], T\_fp c1, T\_fp const v1[], T\_fp c2, T\_fp const v2[])

#### 5.19.1 Detailed Description

#### 5.19.2 Function Documentation

5.19.2.1 `template<class T_fp, int N_len> void vm_VMath< T_fp, N_len >::lincomb ( T_fp res[], T_fp c1, T_fp const v1[], T_fp c2, T_fp const v2[] )` `[inline], [static]`

form linear combination:  $\text{res} = c1 * v1 + c2 * v2$ .

For each `i`:  $\text{res}[i] = c1 * v1[i] + c2 * v2[i]$

#### Parameters

<i>res</i>	result vector
<i>c1</i>	1st T_fp
<i>v1</i>	1st vector
<i>c2</i>	2nd T_fp
<i>v2</i>	2nd vector

Definition at line 441 of file `vm_vmath.h`.

## 5.20 I/O operations.

## Functions

- static std::ostream & `vm_VMath< T_fp, N_len >::print_on` (std::ostream &os, T\_fp const v[], int by, char const prefix[]="", char const postfix[]="")
- static void `vm_VMath< T_fp, N_len >::cprint_on` (FILE \*of, T\_fp const v[], int by, char const prefix[]="", char const postfix[]="")

## 5.20.1 Detailed Description

## 5.20.2 Function Documentation

5.20.2.1 `template<class T_fp, int N_len> void vm_VMath< T_fp, N_len >::cprint_on ( FILE * of, T_fp const v[], int by, char const prefix[] = " ", char const postfix[] = " " ) [inline],[static]`

Print a vector to a FILE\* stream.

## Parameters

<i>of</i>	the FILE*
<i>v</i>	vector to be printed
<i>by</i>	stride by this many
<i>prefix</i>	optional prefix string
<i>postfix</i>	optional postfix string

Definition at line 471 of file vm\_vmath.h.

5.20.2.2 `template<class T_fp, int N_len> std::ostream & vm_VMath< T_fp, N_len >::print_on ( std::ostream & os, T_fp const v[], int by, char const prefix[] = " ", char const postfix[] = " " ) [inline],[static]`

Print a vector to an ostream.

## Parameters

<i>os</i>	the ostream
<i>v</i>	vector to be printed
<i>by</i>	stride by this many
<i>prefix</i>	optional prefix string
<i>postfix</i>	optional postfix string

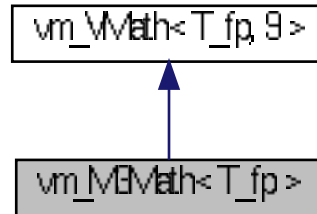
Definition at line 451 of file vm\_vmath.h.

## 6 Class Documentation

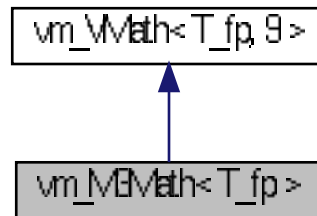
### 6.1 `vm_M3Math< T_fp >` Class Template Reference

```
#include <vm_math/vm_m3math.h>
```

Inheritance diagram for `vm_M3Math< T_fp >`:



Collaboration diagram for `vm_M3Math< T_fp >`:



#### Public Types

- typedef `T_fp` **value\_type**

#### Static Public Member Functions

- static int `at` (int i, int j)
- static void `init_by_row` (`T_fp` m[], `T_fp` const row0[], `T_fp` const row1[], `T_fp` const row2[])
- static void `init_by_col` (`T_fp` m[], `T_fp` const col0[], `T_fp` const col1[], `T_fp` const col2[])
- static void `dyad_product` (`T_fp` m[], `T_fp` const v1[], `T_fp` const v2[])
- static void `inject_row` (`T_fp` m[], `T_fp` const row[], int whichrow)



- static void [inject\\_col](#) (T\_fp m[], T\_fp const col[], int whichcol)
- static void [extract\\_row](#) (T\_fp const m[], T\_fp row[], int whichrow)
- static void [extract\\_col](#) (T\_fp const m[], T\_fp col[], int whichcol)
- static void [mvmult](#) (T\_fp res[], T\_fp const m[], T\_fp const v[])
- static void [mtvmult](#) (T\_fp res[], T\_fp const m[], T\_fp const v[])
- static void [mmult](#) (T\_fp mres[], T\_fp const m1[], T\_fp const m2[])
- static std::ostream & [print\\_on](#) (std::ostream &os, T\_fp const m[], char const prefix[]="", char const postfix[]="")
- static void [cprint\\_on](#) (FILE \*of, T\_fp const m[], char const prefix[]="", char const postfix[]="")

### 6.1.1 Detailed Description

`template<class T_fp>class vm_M3Math< T_fp >`

A template class providing common numerical operations on 3x3-matrices of T\_fp's (floating point type). The matrix is assumed to be stored as a \* contiguous one-dimensional array of 9 T\_fp's, properly aligned for type T\_fp.

The class is a simple class to handle common numerical operations on 3x3-matrices

of floating point T\_fps.

Unless otherwise noted, the operations are component by component, e.g.,

```
mul_eq(m1,m2)
```

results in

```
m1[i][j] += m2[i][j], where i = 0,1,2 and j = 0,1,2.
```

[vm\\_M3Math](#) has only static member functions; there are no data members.

Where possible, the static member functions are inlined.

Definition at line 77 of file `vm_m3math.h`.

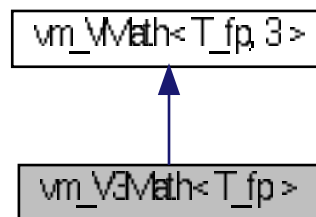
The documentation for this class was generated from the following file:

- `vm_m3math.h`

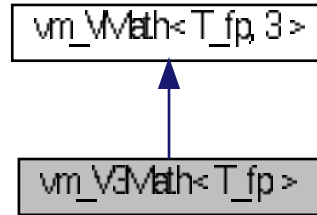
## 6.2 vm\_V3Math< T\_fp > Class Template Reference

```
#include <vm_math/vm_v3math.h>
```

Inheritance diagram for `vm_V3Math< T_fp >`:



Collaboration diagram for `vm_V3Math< T_fp >`:



### Public Types

- typedef `T_fp` [value\\_type](#)

### Static Public Member Functions

- static void [set](#) (`T_fp` v[], `T_fp` x, `T_fp` y, `T_fp` z)
- static void [set](#) (`T_fp` v[], `T_fp` x)
- static `T_fp` [unitize](#) (`T_fp` v[])
- static `T_fp` [unitize](#) (`T_fp` vu[], `T_fp` const vi[])
- static int [is\\_unit\\_vector](#) (`T_fp` const v[], `T_fp` const tol)
- static int [are\\_orthogonal](#) (`T_fp` const v[], `T_fp` const other[], `T_fp` const tol)
- static int [are\\_orthonormal](#) (`T_fp` const v[], `T_fp` const other[], `T_fp` const tol)
- static `T_fp` [dot](#) (`T_fp` const v1[], `T_fp` const v2[])
- static void [cross](#) (`T_fp` prod[], `T_fp` const v1[], `T_fp` const v2[])
- static std::ostream & [print\\_on](#) (std::ostream &os, `T_fp` const v[], char const prefix[]="", char const postfix[]="")
- static void [cprint\\_on](#) (FILE \*of, `T_fp` const v[], char const prefix[]="", char const postfix[]="")

#### 6.2.1 Detailed Description

```
template<class T_fp>class vm_V3Math< T_fp >
```

A template class providing common numerical operations on 3-vectors of `T_fp`'s (floating point type).

Unless otherwise noted, the operations are component by component, e.g.,

```
vm_V3Math<float>::div_eq(v1, v2)
```

corresponds to

```
v1[i] /= v2[i], where i = 0,1,2.
```

[vm\\_V3Math](#) has only static member functions; there are no data members.

Where possible, the static member functions are inlined.

Definition at line 69 of file `vm_v3math.h`.

## 6.2.2 Member Typedef Documentation

6.2.2.1 `template<class T_fp > vm_V3Math< T_fp >::value_type`

A typedef for the floating point type;

Definition at line 83 of file `vm_v3math.h`.

The documentation for this class was generated from the following file:

- `vm_v3math.h`

6.3 `vm_VMath< T_fp, N_len >` Class Template Reference

```
#include <vm_math/vm_vmath.h>
```

## Public Types

- typedef `T_fp` `value_type`

## Static Public Member Functions

- static void `copy` (`T_fp` `v[]`, `T_fp` const `cv[]`)
- static void `set` (`T_fp` `v[]`, `T_fp` `r`)
- static void `add_eq` (`T_fp` `v[]`, `T_fp` const `cv[]`)
- static void `sub_eq` (`T_fp` `v[]`, `T_fp` const `cv[]`)
- static void `mul_eq` (`T_fp` `v[]`, `T_fp` const `cv[]`)
- static void `div_eq` (`T_fp` `v[]`, `T_fp` const `cv[]`)
- static void `add_eq` (`T_fp` `v[]`, `T_fp` `r`)
- static void `sub_eq` (`T_fp` `v[]`, `T_fp` `r`)
- static void `mul_eq` (`T_fp` `v[]`, `T_fp` `r`)
- static void `div_eq` (`T_fp` `v[]`, `T_fp` `r`)
- static void `negate` (`T_fp` `v[]`)
- static void `add` (`T_fp` `v[]`, `T_fp` const `cv1[]`, `T_fp` const `cv2[]`)
- static void `sub` (`T_fp` `v[]`, `T_fp` const `cv1[]`, `T_fp` const `cv2[]`)
- static void `mul` (`T_fp` `v[]`, `T_fp` const `cv1[]`, `T_fp` const `cv2[]`)
- static void `div` (`T_fp` `v[]`, `T_fp` const `cv1[]`, `T_fp` const `cv2[]`)
- static void `add` (`T_fp` `v[]`, `T_fp` const `cv[]`, `T_fp` `r`)
- static void `sub` (`T_fp` `v[]`, `T_fp` const `cv[]`, `T_fp` `r`)
- static void `mul` (`T_fp` `v[]`, `T_fp` const `cv[]`, `T_fp` `r`)
- static void `div` (`T_fp` `v[]`, `T_fp` const `cv[]`, `T_fp` `r`)
- static void `add` (`T_fp` `v[]`, `T_fp` `r`, `T_fp` const `cv[]`)
- static void `sub` (`T_fp` `v[]`, `T_fp` `r`, `T_fp` const `cv[]`)
- static void `mul` (`T_fp` `v[]`, `T_fp` `r`, `T_fp` const `cv[]`)
- static void `div` (`T_fp` `v[]`, `T_fp` `r`, `T_fp` const `cv[]`)
- static void `lincomb` (`T_fp` `res[]`, `T_fp` `c1`, `T_fp` const `v1[]`, `T_fp` `c2`, `T_fp` const `v2[]`)
- static `std::ostream` & `print_on` (`std::ostream` &`os`, `T_fp` const `v[]`, `int` `by`, `char` const `prefix[]=""`, `char` const `postfix[]=""`)
- static void `cprint_on` (`FILE` \*`of`, `T_fp` const `v[]`, `int` `by`, `char` const `prefix[]=""`, `char` const `postfix[]=""`)

### 6.3.1 Detailed Description

`template<class T_fp, int N_len>class vm_VMath< T_fp, N_len >`

A template class providing common numerical operations on `N_len`-long 1 dimensional arrays of `T_fp`.

`T_fp` is a floating point type.

`N_len` is the length of the vector.

The array data are assumed to be stored as a contiguous one-dimensional array of `N_len` `T_fp`'s, properly aligned for type `T_fp`.

Unless otherwise noted, the operations are component by component, e.g.,

```
vm_VMath<float,4>::mul(prod, v1, v2)
```

corresponds to

```
prod[i] = v1[i] * v2[i], where i = 0,1,2,3.
```

`vm_VMath` has only static member functions; there are no data members.

Where possible, the static member functions are inlined.

Definition at line 78 of file `vm_vmath.h`.

### 6.3.2 Member Typedef Documentation

#### 6.3.2.1 `template<class T_fp, int N_len> vm_VMath< T_fp, N_len >::value_type`

a typedef for the floating point type;

Definition at line 91 of file `vm_vmath.h`.

The documentation for this class was generated from the following file:

- `vm_vmath.h`

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